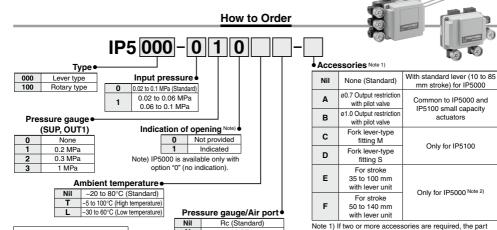
Pneumatic-Pneumatic Positioner (Lever type/Rotary type)

IP5000/5100 Series

• JIS F8007 IP55



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Precautions

- Avoid impact to positioner while transporting and handling.
- Operate within specified temperature range to prevent deterioration of seals.
- Attach a body cover to the positioner when it is in use or left in the field in order to avoid rain water.
- 4. Take measures to avoid dew condensation if the positioner is exposed to high temperature and humidity during transportation or storage or when it is left on the site.
- The zero point is subject to the mounting position. Adjust zero point after installation on the site.
- 6. As the positioner contains extra-fine orifices such as restrictor and nozzle, if drain or dust is present in the supply pressure line, malfunction (+1) may resuit. In addition to an air filter (SMC Series AF), it is recommended to use a mist separator (SMC Series AM, AFM) and a micro mist separator (SMC Series AMD, AFD).
 - Also, refer to "SMC Air Preparation System" for air quality.
- 7. Never use a lubricator, as this can cause a malfunction (*1).
- *1 If the restrictor is clogged, output from the OUT1 port of the positioner may occur continuously or hunching and overshoot may occur.

Specifications^{Note 1)}

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Туре	IP5000		IP5100			
	Lever type lever feedback		Rotary type cam feedback			
Item	Single action	Double action	Single action	Double action		
Supply pressure	0.14 to 0.7 MPa					
Input pressure	0.02 to 0.1 MPa					
Standard stroke	10 to 85 mm		60° to 100° Note 3)			
Sensitivity Note 4)	Within 0.1% F.S.	Within 0.5% F.S.				
Linearity Note 2, 4)	Within ±1% F.S.	Within ±2% F.S.				
Hysteresis Note 2, 4)	Within 0.75% F.S.	Within 1% F.S.				
Repeatability Note 4)	Within ±0.5% F.S.					
Air consumption Note 5)	5 L/min (ANR) or less (SUP = 0.14 MPa)Note)		11 L/min (ANR) or less (SUP = 0.4 MPa) ^{Note)}			
Output flow rate Note 5)	80 L/min (ANR) or more (SUP = 0.14 MPa)Note) 200 L/min (ANR) or more (SUP = 0.4 I		re (SUP = 0.4 MPa)Note)			
Ambient and fluid temperature	-20°C to 80°C (Standard)					
Coefficient of temperature	Within 0.1% F.S./°C					
Air connection port Note 6)	Rc1/4 (Standard)					
Main component parts	Aluminum die-cast, Stainless steel, Brass, Nitrile rubber					
Weight	Approx. 1.4 kg		Approx. 1.2 kg			
Dimensions	118 x 102 x 86 (Body)		118 x 92 x 77.5 (Body)			

Note 1) Specification values are given at normal temperature (20°C). Note 2) 1/2 Split range (Standard) For operation with 1/2 split range, the linearity and hysteresis should be 1% F.S. higher than the above specifications.

Note 3) Stroke adjustment: 0 to 60°, 0 to 100°

Note 4) Characteristics relating to accuracy differ depending on combination with other constituent loop equipment, such as positioners and actuators.

numbers should be given in alphabetical order.

Note 2) For "E" and "F", standard lever is not provided.

Ex.) IP5000-010-AD

Note 5) Air consumption is due to exhaust from nozzle. And (ANR) indicates JIS B0120 standard air. Note 6) Thread type can be specified by model selection.

Replacement Parts

Part no.	Description	Note
P378010-10	Pilot valve unit	For IP5000
P378020-11	Pilot valve unit	For IP5100
P368010-24	Fork lever assembly M	For IP5100 (Accessory: C)
P368010-25	Fork lever assembly S	For IP5100 (Accessory: D)
P378010-11	Feedback lever	For IP5000/10 to 85 mm (Accessory: Nil)
P378010-12	Feedback lever	For IP5000/35 to 100 mm (Accessory: E)
P378010-13	Feedback lever	For IP5000/50 to 140 mm (Accessory: F)

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IP5000/5100 Series

Principle of Operation

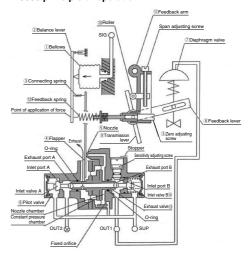
IP5000 type

When the input pressure applied to the SIG port of the positioner increases, bellows ① press balance lever ② to the left. As this movement moves flapper ④ to the left through connecting spring ③, the gap between nozzle ⑤ and flapper ④ widens, and the nozzle back pressure of pilot valve ⑥ drops. As a result, the pressure balance in the constant pressure chamber is broken, and exhaust valve ⑥ presses inlet valve B ⑭ to the right, thus opening inlet port B. Then, output pressure OUT1 rises, and driven diaphragm ⑦ moves downward.

The movement of diaphragm valve ⑦ deflects feedback arm ⑪ to the right through feedback lever ⑧, transmission lever ⑨, and roller ⑩. Such deflection increases the tension of feedback spring ⑫ and acts on balance lever ②.

Since driven diaphragm ⑦ moves until the tensile force of feedback spring ⑫ and the force generated by bellows ① balance, it is always set in the position proportional to the input pressure. When the signal air pressure decreases, the operation is reversed.

IP5000 principle of operation



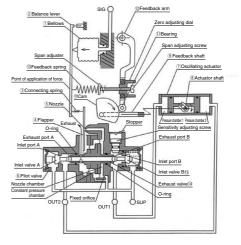
IP5100 type

When the input pressure applied to the SIG port of the positioner increases, bellows ① press balance lever ② to the left. As this movement moves flapper ④ to the left through connecting spring ③, the gap between nozzle ⑤ and flapper ④ widens, and the nozzle back pressure of pilot valve ⑥ drops. As a result, the pressure balance in the constant pressure chamber is broken, and exhaust valve ⑭ presses inlet valve B ⑯ to the right. Then, inlet port B opens, and output pressure OUT1 increases.

In the meantime, the movement of exhaust valve 4 to the right opens exhaust port A, and output pressure OUT2 decreases. Therefore, pressure difference is generated between pressure chamber 1 and pressure chamber 2 of oscillating actuator 2, and actuator shaft 8 turns in the direction of the arrow. The movement of actuator shaft 9 deflects feedback arm 2 to the right through feedback shaft 9, cam 0, and bearing 1. Such deflection increases the tension of feedback spring 3 and acts on balance lever 2.

Since oscillating actuator moves until the tensile force of feedback spring and the force generated by bellows balance, it is always set in the position proportional to the input pressure. When the signal air pressure decreases, the operation is reversed.

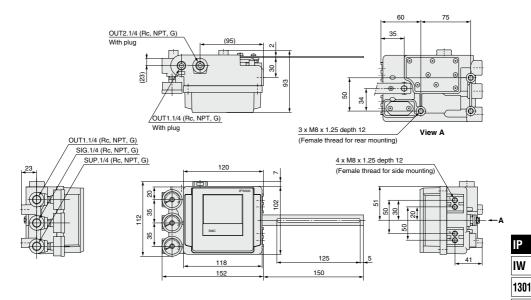
IP5100 principle of operation



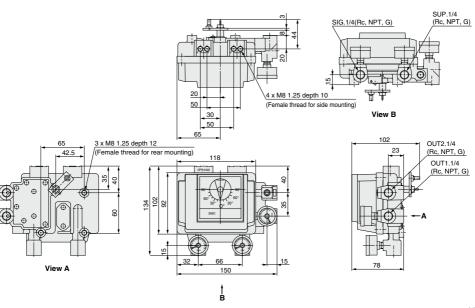
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Dimensions

IP5000 type (Lever type lever feedback)



IP5100 type (Rotary type cam feedback)



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IL2□

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